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2006 J. Phys. A: Math. Gen. 39 14241

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A second-order accurate lattice Boltzmann non-Newtonian flow model

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Received 2 June 2006, in final form 9 October 2006

Published 1 November 2006

Online at stacks.iop.org/JPhysA/39/14241

Abstract

A second-order accurate lattice Boltzmann model is presented for non-Newtonian flow. The non-Newtonian nature of the flow is implemented using a power law model. This is used to enable the accuracy of the model to be assessed and is not a limitation of the model. The second-order accuracy is demonstrated for a range of power law model parameter values representing shear thinning and shear thickening fluids. These results are compared with those of Gabbanelli *et al* (2006 *Phys. Rev. E* **72** 046312) and it is noted that a higher order of accuracy and greater computational efficiency are achieved. These results demonstrate the suitability of the LBM for shear-dependent non-Newtonian flow simulations.

PACS numbers: 47.11.–j, 47.11.Qr, 47.50.–d

1. Introduction

The study of non-Newtonian fluids and their flow properties is of interest in many fields of research, including geophysics (Ashby and Verrall 1977), hydrology (Federico 1998), material sciences (Bird and West 1995) and physiological modelling (Nichols and O'Rourke 2005). In many cases of interest, analytic solutions do not exist due to complex geometries and non-Newtonian properties of the flow. Thus numerical simulation becomes a valuable investigative tool.

In this paper we will consider a lattice Boltzmann method (LBM) for the simulation of non-Newtonian fluids. The LBM is a second-order accurate method for simulating fluid flow that uses a simplified kinetic equation. It has been applied to many general problems including turbulence (Cosgrove *et al* 2003), magnetohydrodynamics (Chen *et al* 1991), porous media flow (Manz *et al* 1999) multiphase flows (Swift *et al* 1996) and blood flow (Fang *et al* 2002, Tamagawa and Matsuo 2004, Artoli *et al* 2004, Boyd *et al* 2005, Yi *et al* 2005) as well as to

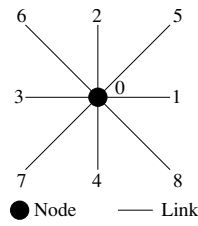


Figure 1. The D2Q9 lattice. The black circle is the node, and the lines are the link directions, numbered from 1 to 8.

non-Newtonian flows (Gabbanelli *et al* 2006). The underlying lattice structure and the local nature of the calculation makes it ideal for parallel implementation (Kandhai *et al* 1998).

In this paper, a non-Newtonian fluid flow model simulated using the LBM will be described and its accuracy will be demonstrated in a two-dimensional rigid pipe flow. A power law model is used to describe the non-Newtonian nature of the fluid. This model is used to enable comparison of the results with an analytic solution, but is not a restriction of the technique. It is found that the LBM retains second-order accuracy for this non-Newtonian flow, demonstrating the suitability of the LBM for shear-dependent non-Newtonian flow simulations, including those that involve more complicated constitutive fluid descriptions.

2. Theoretical background

2.1. The lattice Boltzmann method

The lattice Boltzmann method (Chen and Doolen 1998) has recently been developed as an alternative method for simulating a range of fluid flows. In the LBM particle distribution functions, $f_i(\mathbf{x}, t)$ at point \mathbf{x} at time t , are confined to move synchronously on a regular lattice. The distribution functions interact on the lattice in a way that conserves mass, momentum, isotropy and Galilean invariance. Here i labels the lattice link the distribution function is on. The lattice used in this paper is the D2Q9, shown in figure 1.

The evolution of the distribution functions on the lattice is governed by the discrete Boltzmann equation (Chen and Doolen 1998)

$$f_i(\mathbf{x} + \mathbf{e}_i \Delta x, t + \Delta t) = f_i(\mathbf{x}, t) + \Omega_i(\mathbf{x}, t), \quad (i = 0, 1, \dots, M), \quad (1)$$

where for the D2Q9 lattice, see figure 1,

$$\begin{aligned} \mathbf{e}_0 &= (0, 0), & (i = 0), \\ \mathbf{e}_i &= \left(\cos\left(\frac{\pi}{2}(i-1)\right), \sin\left(\frac{\pi}{2}(i-1)\right) \right), & (i = 1, 2, 3, 4), \end{aligned} \quad (2)$$

$$\mathbf{e}_i = \sqrt{2} \left(\cos\left(\frac{\pi}{2}(i-1) + \frac{\pi}{4}\right), \sin\left(\frac{\pi}{2}(i-1) + \frac{\pi}{4}\right) \right), \quad (i = 5, 6, 7, 8),$$

and Ω_i is the collision operator. The fluid density ρ and velocity \mathbf{u} can be calculated directly from the distribution functions at each node by

$$\rho = \sum_i f_i \quad \text{and} \quad \rho \mathbf{u} = \sum_i f_i \mathbf{e}_i. \quad (3)$$

It is assumed that the distribution functions f_i can be expanded formally around a local equilibrium distribution such that

$$f_i = f_i^{\text{eq}} + \varepsilon f_i^{\text{neq}}, \quad (4)$$

where ε is a small parameter often taken to be the Knudson number, f_i^{eq} are equilibrium distribution function and f_i^{neq} are non-equilibrium distributions functions. f_i^{eq} is selected such that

$$\rho = \sum_i f_i^{\text{eq}} \quad \text{and} \quad \rho \mathbf{u} = \sum_i f_i^{\text{eq}} \mathbf{e}_i, \quad (5)$$

and it is assumed that the non-equilibrium distribution functions, f_i^{neq} , can be further expanded as

$$f_i^{\text{neq}} = f_i^{(1)} + \varepsilon f_i^{(2)} + o(\varepsilon^2), \quad (6)$$

where

$$\sum_i f_i^{(k)} = \sum_i f_i^{(k)} \mathbf{e}_i = 0, \quad k = 1, 2. \quad (7)$$

The collision operator Ω_i is given by the Bhatnagar–Gross–Krook approximation as (Bhatnagar *et al* 1954, Chen and Doolen 1998)

$$\Omega_i = -\frac{1}{\tau} [f_i(\mathbf{x}, t) - f_i^{\text{eq}}(\mathbf{x}, t)], \quad (8)$$

where τ is the relaxation time. The equilibrium form of the distribution function in two dimensions for the D2Q9 lattice is given by (Quian *et al* 1992)

$$f_i^{\text{eq}}(\mathbf{x}, t) = w_i \rho \left(1 + 3\mathbf{e}_i \cdot \mathbf{u} + \frac{9}{2} (\mathbf{e}_i \cdot \mathbf{u})^2 - \frac{3}{2} \mathbf{u}^2 \right) \quad (9)$$

where $w_0 = 4/9$, $w_i = 1/9$ for $i = 1, 2, 3, 4$ and $w_i = 1/36$ for $i = 5, 6, 7, 8$. The relaxation time τ is related to the kinematic viscosity ν by

$$\nu = \frac{2\tau - 1}{6}. \quad (10)$$

The LBM reproduces the Navier stokes equation in the nearly incompressible limit and is second-order accurate in the body of the fluid (Chen and Doolen 1998).

The stress tensor for an incompressible fluid with pressure p is given by

$$\sigma_{\alpha\beta} = -p\delta_{\alpha\beta} + 2\eta S_{\alpha\beta}, \quad (11)$$

where $\delta_{\alpha\beta}$ is the Kronecker delta and

$$S_{\alpha\beta} = \frac{1}{2} (\nabla_\beta u_\alpha + \nabla_\alpha u_\beta) \quad (12)$$

is the strain rate tensor.

It can be shown (Artoli 2003) that $S_{\alpha\beta}$ can be calculated locally at each node in the LBM as

$$S_{\alpha\beta} = -\frac{3}{2\tau} \sum_i f_i^{(1)} \mathbf{e}_{i\alpha} \mathbf{e}_{i\beta}. \quad (13)$$

The $f_i^{(1)}$ terms are usually calculated as part of the velocity calculations in the LBM algorithm. Thus calculating shear in this manner is efficient since it removes the need to calculate derivatives of the velocity. Further, the shear is calculated locally, which is particularly advantageous if the LBM is being implemented in parallel.

2.2. The power law model

In the following discussion we denote the second invariant of the strain rate tensor as

$$D_{II} = \sum_{\alpha, \beta=1}^l S_{\alpha\beta} S_{\alpha\beta}, \quad (14)$$

where $l = 2$ in the case of a two-dimensional model. The shear rate is then defined as

$$\dot{\gamma} = 2\sqrt{D_{II}}. \quad (15)$$

The power law model is one of the simplest generalizations of non-Newtonian flow. In this model the apparent viscosity is given by (Quarteroni *et al* 2000)

$$\nu(\dot{\gamma}) = m|\dot{\gamma}|^{n-1}, \quad (16)$$

where m and n are parameters that are usually obtained by fitting equation (16) to physical viscometric data. This model has the following analytic solution for a simple steady flow in a rigid two-dimensional pipe (Robson 2003):

$$u(y) = \left(\frac{G}{2m}\right)^{\frac{1}{n}} \left(\frac{n}{n+1}\right) \left[\left(\frac{L}{2}\right)^{\frac{n+1}{n}} - \left(\left|\frac{L}{2} - y\right|\right)^{\frac{n+1}{n}} \right], \quad (17)$$

where L is the pipe diameter and $G = -\frac{dp}{dx}$ is the pressure gradient driving the flow.

The value of the parameter n determines the response of the fluid to changes in shear rate, for $n < 1$ the fluid is shear thinning, for $n = 1$ the fluid is Newtonian and for $n > 1$ the fluid is shear thickening.

We note that for a shear thinning fluid (i.e. $n < 1$), $\lim_{\dot{\gamma} \rightarrow 0} m|\dot{\gamma}|^{n-1} = \infty$. Also, the units of m are $m^2 s^{n-2}$, and thus this parameter cannot be associated with any physical properties of the fluid.

Equation (16) can be non-dimensionalized to produce the following dimensionless number analogous to the Reynold's number:

$$Re_{PL} = \frac{u_0^{2-n} L^n}{m}, \quad (18)$$

where m and n are the power law parameters and u_0 is the maximum velocity in a pipe of width L .

3. Methods and results

Power law non-Newtonian flow was implemented in the LBM through the coupling of equations (10) and (16), giving a shear-dependent relaxation time τ at each node. Calculation of shear stress, and hence shear strain, was done via equation (13). Simulations were run at $Re_{PL} = 100$ for n parameters of $n = 0.25, 0.5, 0.75, 1.0$ and 1.25 in order to test the LBM accuracy for a range of non-Newtonian behaviours. A sub-grid accurate second-order boundary scheme (Guo *et al* 2002) was used to implement the pipe geometry.

G , L and m were varied in the simulations in a manner that ensured the Mach number was < 0.03 in order to avoid incompressibility artefacts. The simulations were run until the following criterion was satisfied

$$\sum_{\mathbf{x}} \|\mathbf{u}(\mathbf{x}, t) - \mathbf{u}(\mathbf{x}, t-1)\| < \hat{\epsilon}, \quad (19)$$

where $\hat{\epsilon}$ was a small number taken to be $\hat{\epsilon} = 1 \times 10^{-10}$.

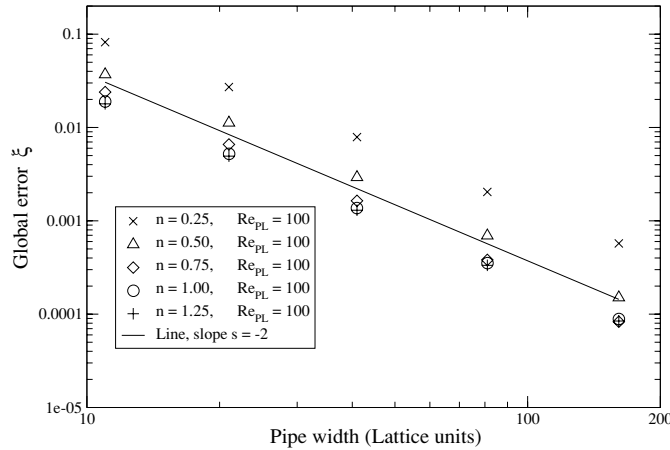


Figure 2. Global error for power law model flow. The black line represents a line of slope -2 , indicating second-order behaviour.

The solutions obtained were compared to the analytic solution given in equation (17), and the global error,

$$\xi = \frac{\sum_{\mathbf{x}} \|\mathbf{u}_b(\mathbf{y}) - \mathbf{u}_a(\mathbf{y})\|}{\sum_{\mathbf{x}} \|\mathbf{u}_a(\mathbf{y})\|}, \quad (20)$$

was calculated, where the subscript a refers to the exact analytic solution and the subscript b refers to the simulated Boltzmann value. Results for the global error are shown in figure 2.

The black line in figure 2 represents a line of slope -2 , indicating second-order behaviour. It is observed that the data presented for the different n parameters closely match the slope of this line. Larger errors occur for smaller n values.

Figures 3(a)–(d) show the normalized analytic velocity profiles (solid lines) compared to the LBM results (circles) for parameter values (a) $n = 0.25$, (b) $n = 0.50$, (c) $n = 0.75$ and (d) $n = 1.25$. It can be seen that the LBM accurately simulates the correct velocity profile for both shear thinning ($n < 1$) and shear thickening ($n > 1$) flows.

For $n < 1$ we see a general flattening of the velocity profile, with flatter velocity profiles corresponding to lower n . Conversely, the profile for $n = 1.25$ shows greater curvature near the central peak velocity. This phenomena can be seen more clearly in figure 4, which shows a comparison of the normalized flow profiles over the range of n parameter values.

4. Discussion

Figure 2 shows that the LBM retains second-order accuracy in the case of a two-dimensional power law flow through a rigid pipe. This method is an improvement over the approach of Gabbanelli *et al* (2006), who used a first-order finite difference method (Aharanov and Rothman 1993) to estimate shear, obtaining only first-order accurate results. The model presented here represents an improvement to a second-order accurate model and an increase in the computational efficiency of the algorithm.

The simulated velocity profiles shown in figure 3 closely match the profiles of the analytic solution for all parameters of n . The largest difference can be seen for $n = 0.25$, where the

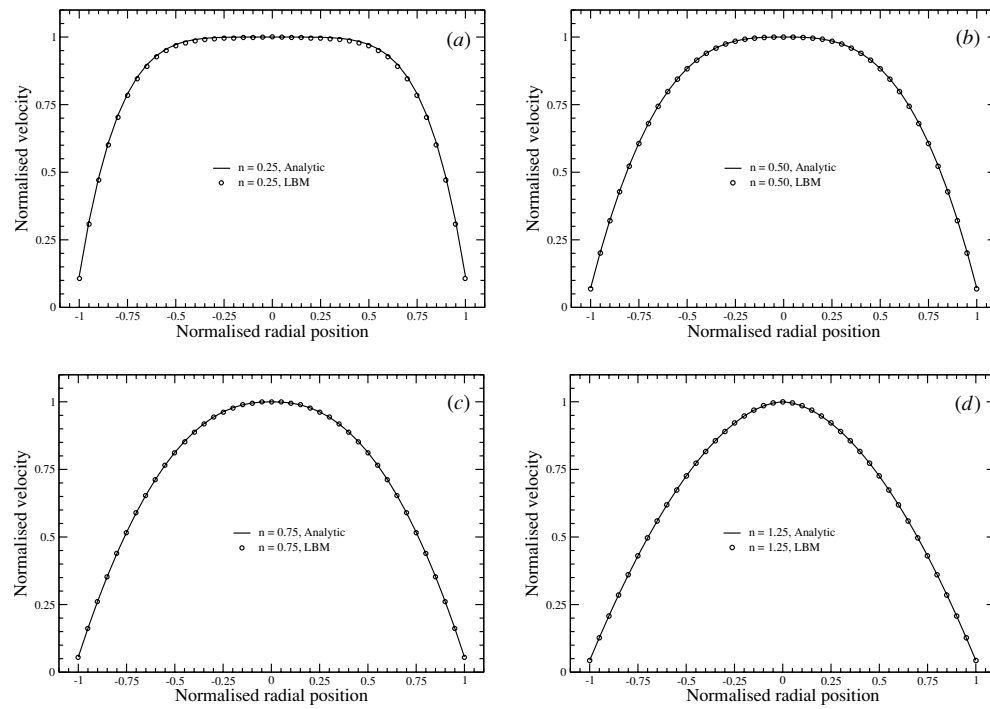


Figure 3. Velocity profile comparisons between the LBM and analytic solutions for power law model flows corresponding to parameter values of (a) $n = 0.25$, (b) $n = 0.50$, (c) $n = 0.75$ and (d) $n = 1.25$.

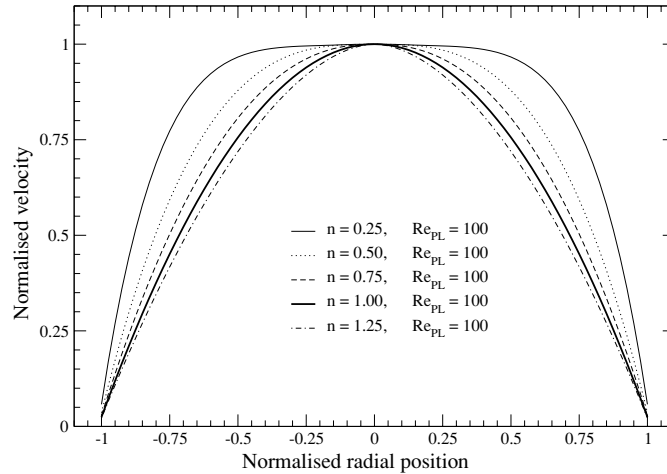


Figure 4. Normalized power law model flow velocity profiles. The thick black line indicates a standard Newtonian parabolic profile.

LBM profile shows slightly less flattening around the central peak velocity compared to the analytic solution.

5. Conclusion

A second-order accurate LBM for shear-dependent non-Newtonian flow has been proposed. This method avoids time consuming derivations of the velocity data to calculate the shear. These results indicate that the LBM is suitable for simulating shear-dependent non-Newtonian flows, including fluids with more complicated constitutive equations.

Acknowledgments

This work was partially supported by Sigma Xi Grant no 10040015 and the Australian Postgraduate Award (APA); this assistance is gratefully acknowledged.

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